



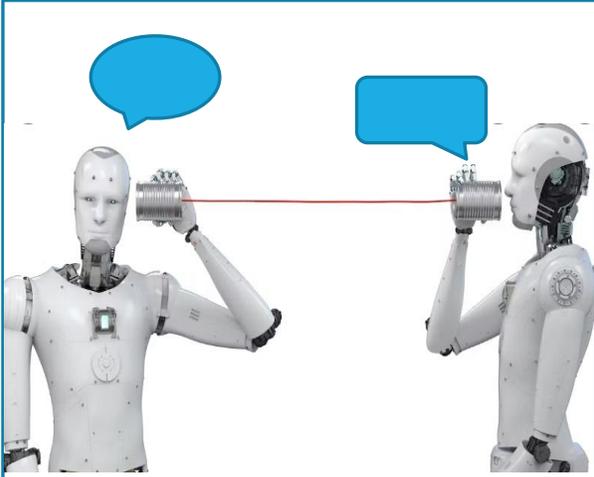
# Extrapolative Continuous-time Bayesian Neural Network for **Fast Training-free** **Test-time Adaptation**

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XIANGMING GU, HAO WANG, CHANG XIAO, HONGFU LIU, YE WANG

# Background: mainstream artificial intelligence (AI)



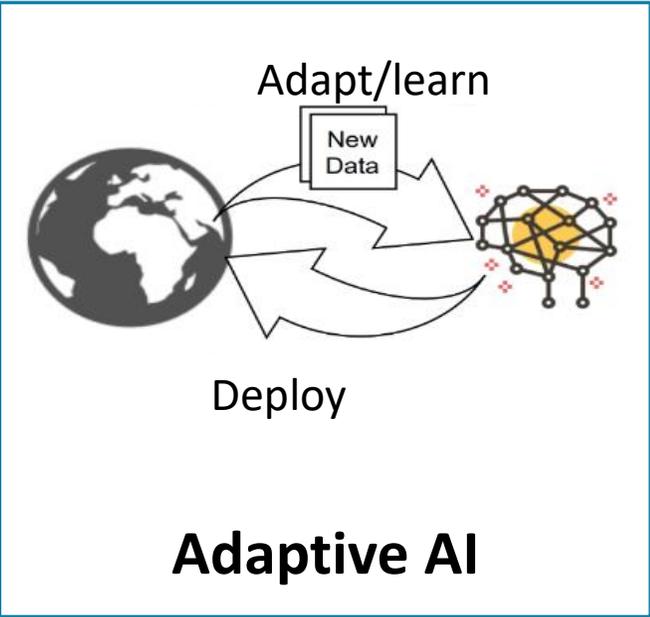
Two humanoid robots are shown in profile, facing each other. Each robot is holding a megaphone to its mouth. A red laser line connects the two megaphones. Above each robot is a blue speech bubble. The entire scene is enclosed in a blue-bordered box.

**Conversational AI**



A 3x3 grid of diverse AI-generated images. The top row shows a woman's face, a horse with a robot on its back, and a fox. The middle row shows astronauts in space, a bowl of glowing purple soup, and two teddy bears. The bottom row is a spectrogram. The entire grid is enclosed in a blue-bordered box.

**Generative AI**



# Background: brain-informed artificial intelligence (BAI)



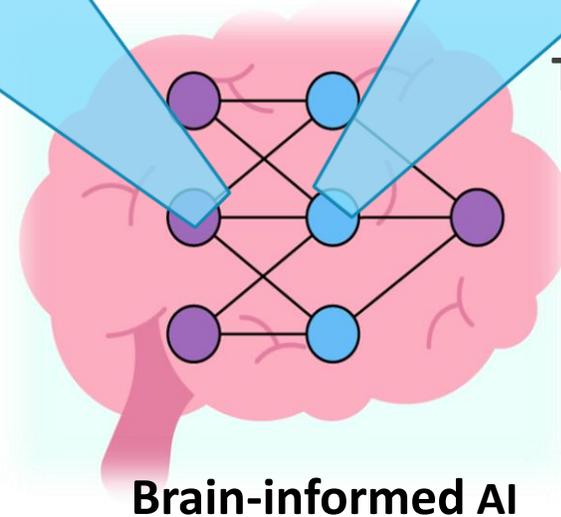
## Brain-informed component

- Modern theories and bio-solutions in Brain science



## Task-specific component

- Target tasks in mainstream AI
- Conversational AI [Huang, et al. ICML 2020]
- Generative AI [Huang, et al. ICML 2021]



# Background: brain-informed artificial intelligence (BAI)



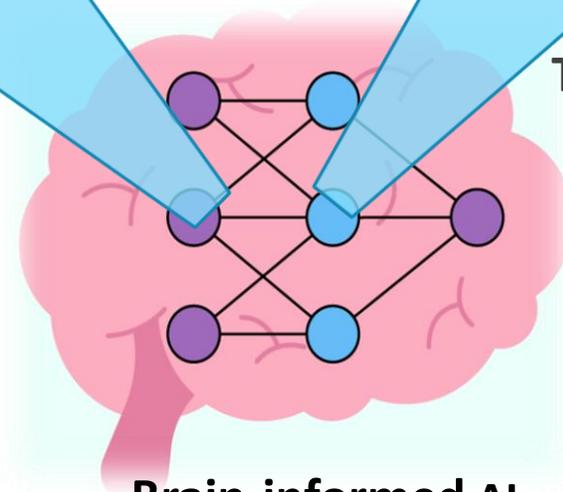
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## Brain-informed AI

This work focus on adaptive AI. [Huang, et al. NeurIPS 2022]

# Motivation: bio-adaptation **vs** artificial-adaptation

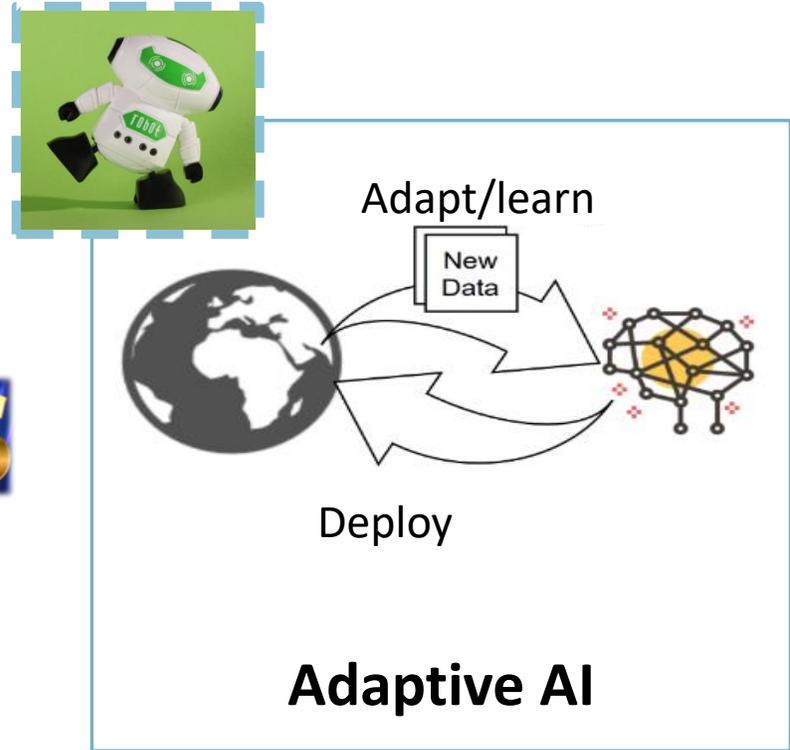
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# Motivation: bio-adaptation **VS** artificial-adaptation

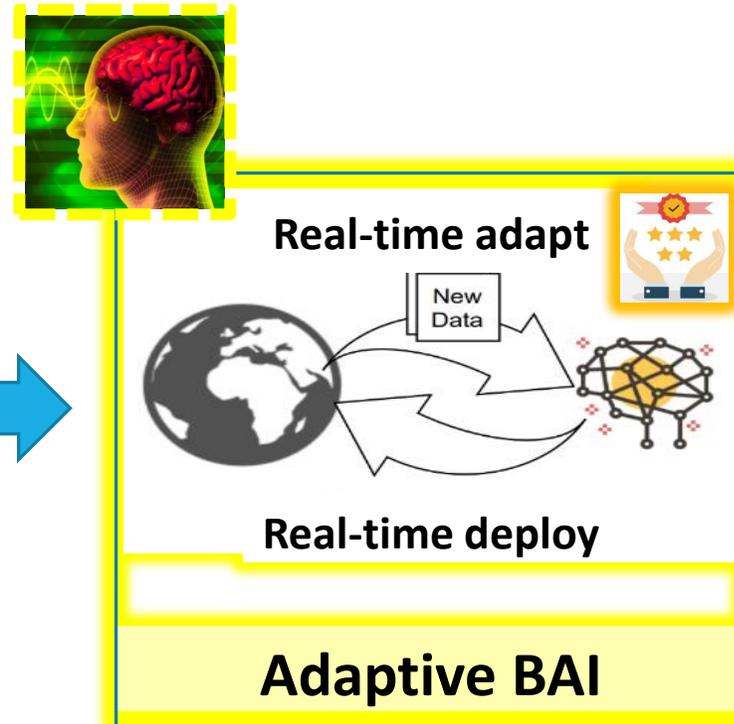
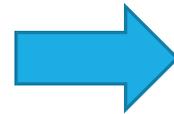
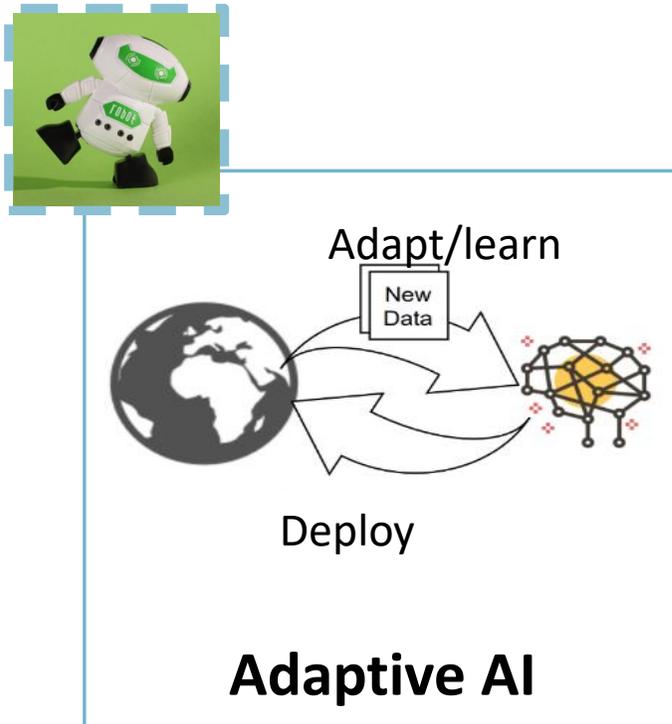


**VS**



Fail to handle non-stationary data in real-time.

# Research goal: from adaptive AI to **adaptive BAI**



Unsupervised domain adaptation (UDA)

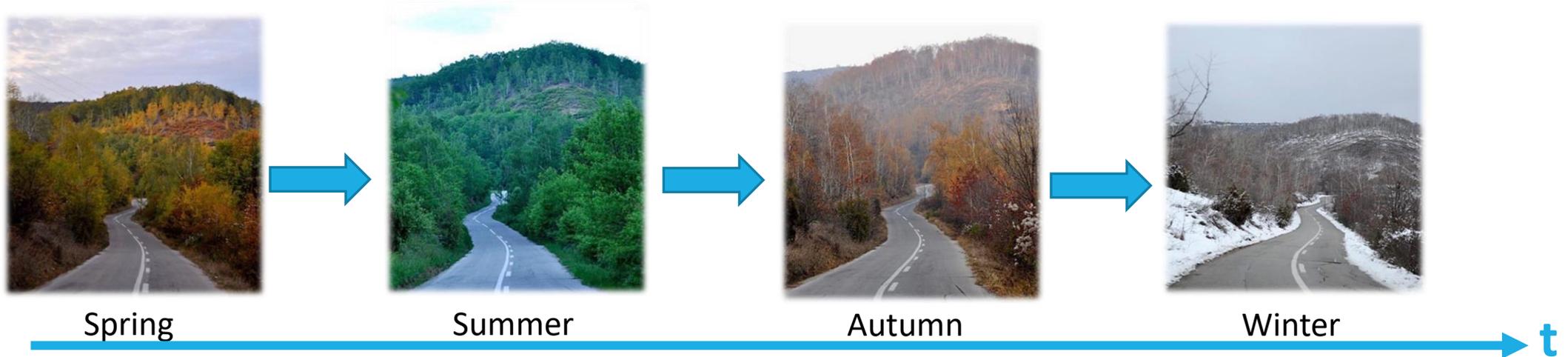
- **Non-stationary** (time-evolving) environment
- Labeled source domain and unlabeled target domain
- **Effectively** and **efficiently** learn from **testing data**
- **Training-free** **test-time adaptation**

# Bio-solution: internal predictive modeling

An mechanism that supports bio-adaptation, which allows organisms to **immediately** and **continuously** adapt to **non-stationary environment**.

## Key features:

- ① Capture the statistics and dynamics of surrounding environment

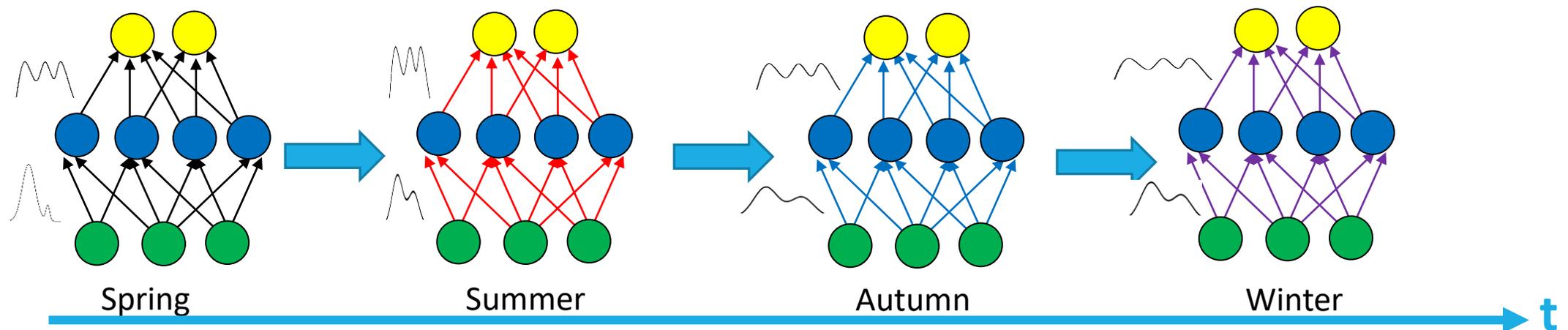


# Bio-solution: internal predictive modeling

An mechanism that supports bio-adaptation, which allows organisms to **immediately** and **continuously** adapt to **non-stationary environment**.

## Key features:

- ② Continually update an internal model based on “the learned dynamics”

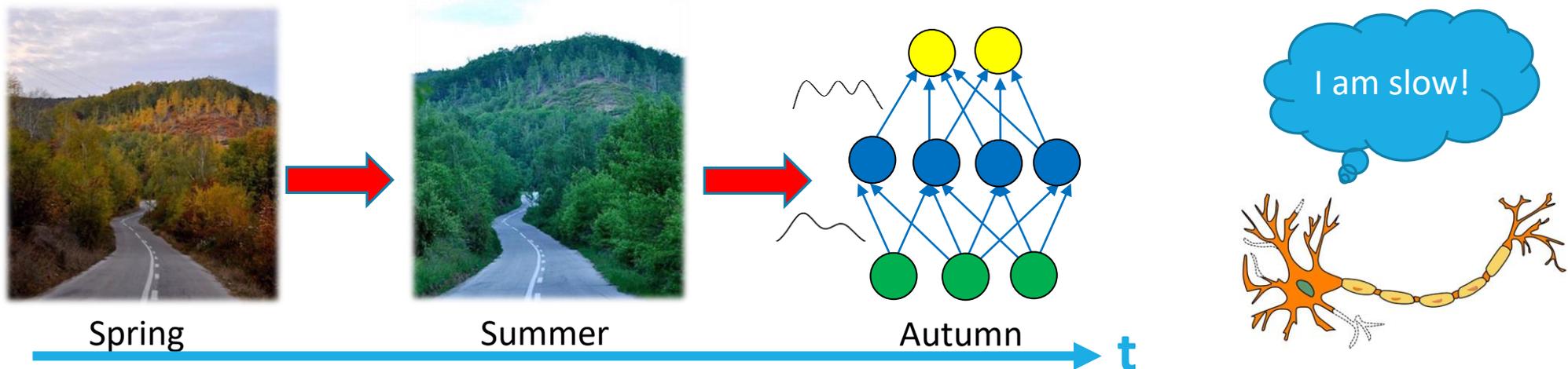


# Bio-solution: internal predictive modeling

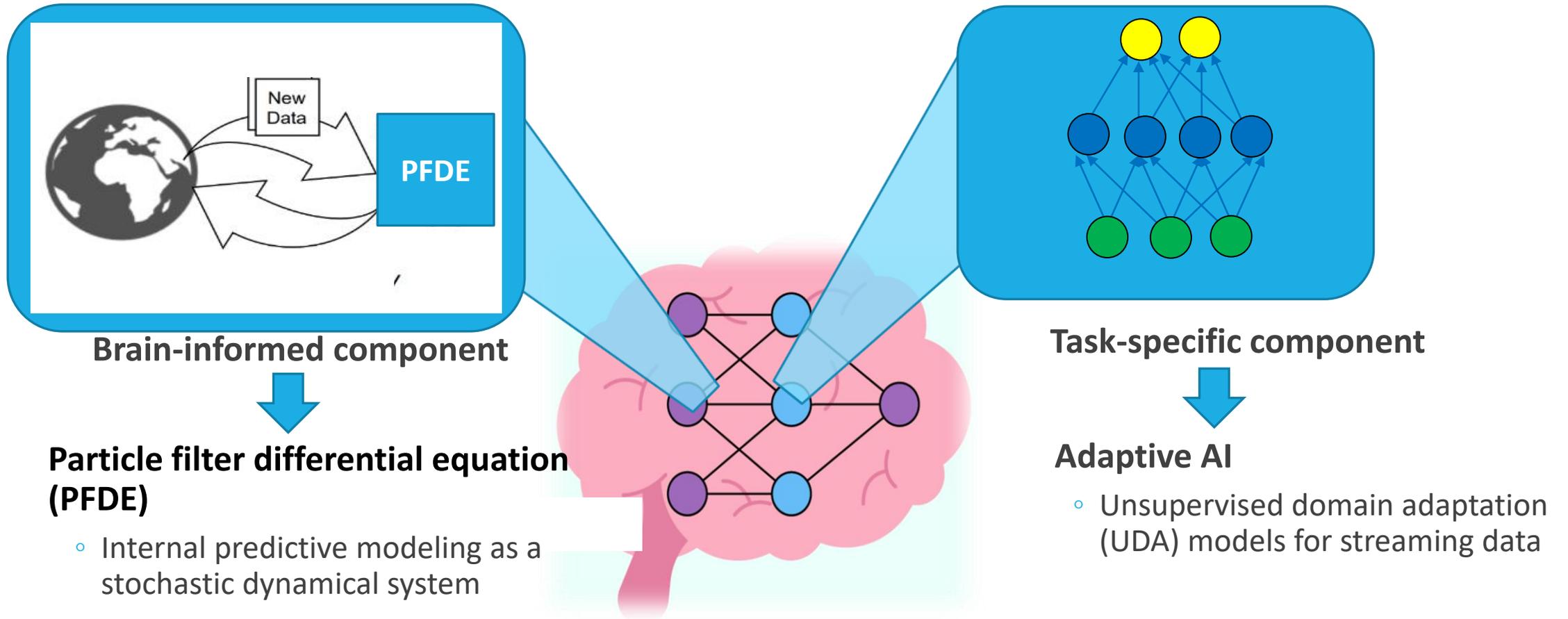
An mechanism that supports bio-adaptation, which allows organisms to **immediately** and **continuously** adapt to **non-stationary environment**.

## Key features:

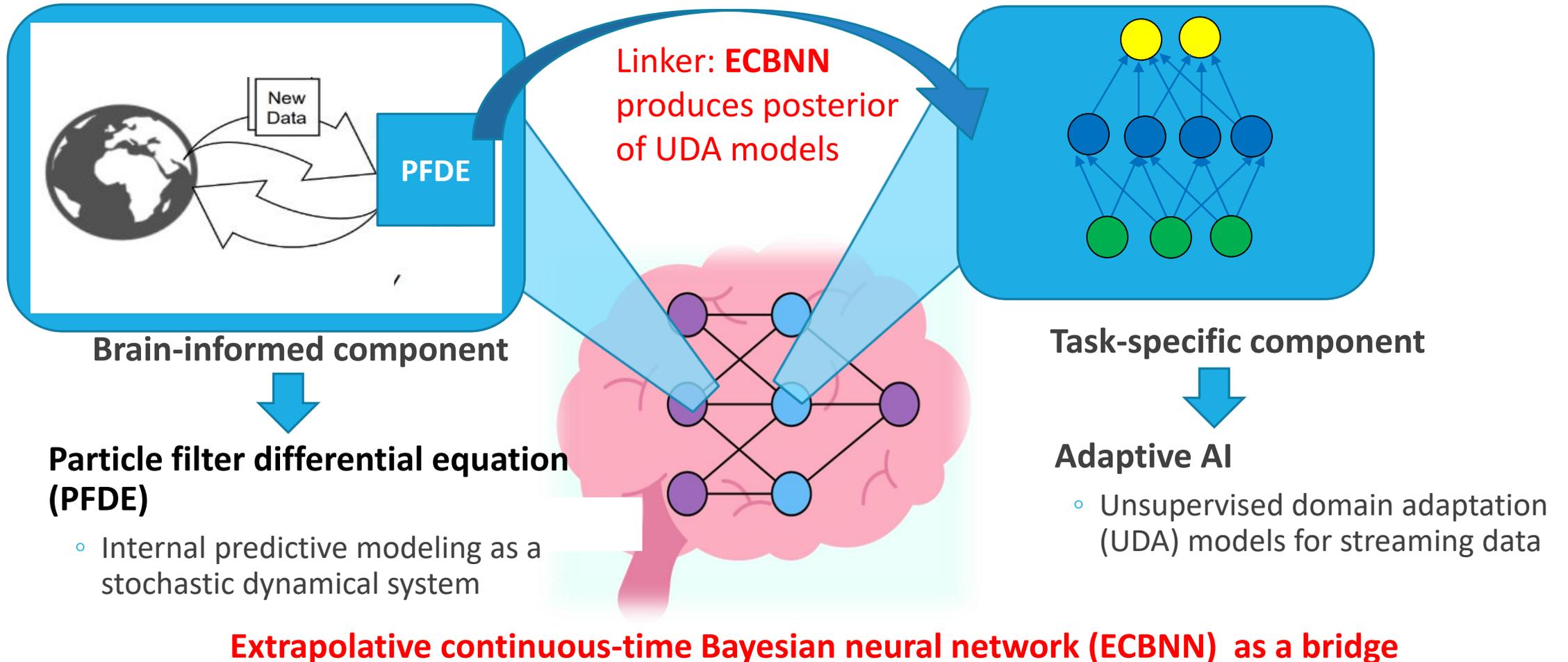
- Effectively learn from history data to generate the “future model”, reducing latency and overcoming neural transmission delays.



# Overview: connecting internal predictive modeling with adaptive AI



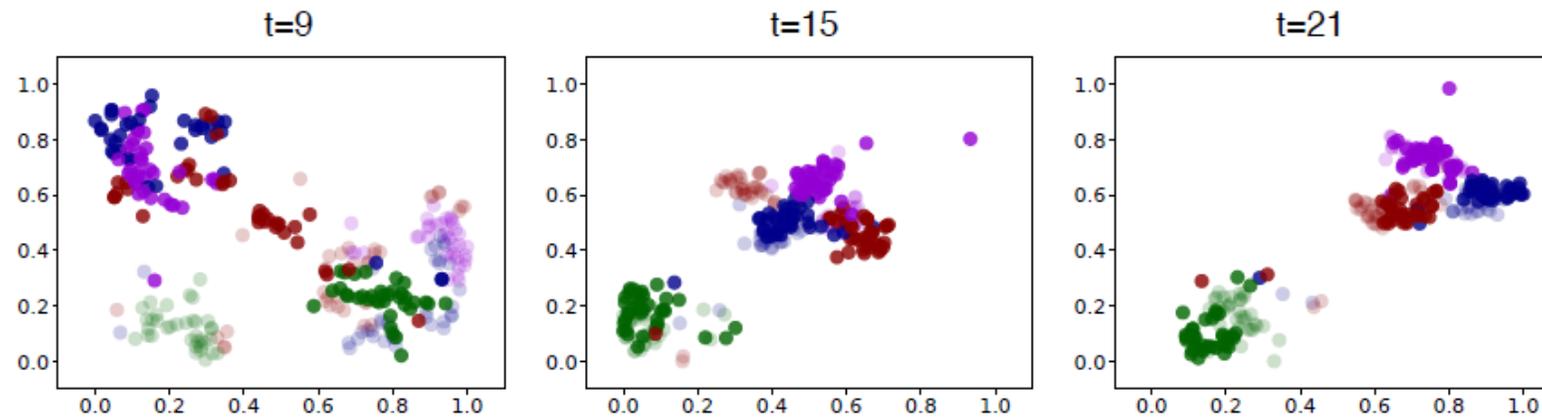
# Overview: connecting internal predictive modeling with adaptive AI



# Temporal-domain invariance for streaming data

## Major challenge:

- Impractically aligning over partial observation of the stream leads to poor alignment quality
  - This work propose to align over the entire data generation mechanism (represented by PFDE)
  - Though such operation is intractable, we provide an analytical upper bound for achieving the temporal-domain invariance (Theorem 2)



**Alignment are gradually improved during real-time testing!**

# Internal predictive modelling as a stochastic dynamical system

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Our particle filter differential equation (PFDE)  
(Theorem 1)

$$\left( \log w(t)^{(j)} \right)' = \left( \log p(\theta(t)^{(j)} | \theta(t - \tau)^{(j)}) \right)'$$

# Internal predictive modelling as a stochastic dynamical system

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Importance weight

Transition distribution

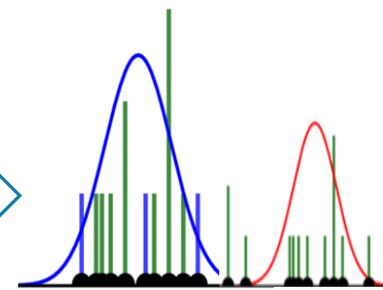
# Internal predictive modelling as a stochastic dynamical system

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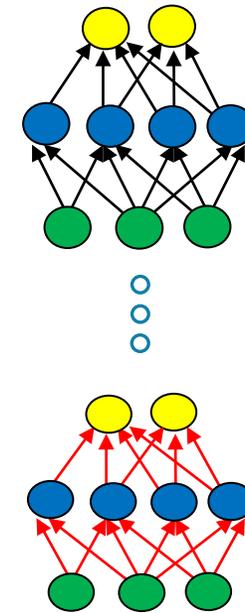
$$\left( \log w(t)^{(j)} \right)' = \left( \log p(\theta(t)^{(j)} | \theta(t - \tau)^{(j)}) \right)'$$

Importance weight      Transition distribution

Solve PFDE  
at time t



Model Posterior  
at time t



Model parameters  
of UDA

# Quantitative results on streaming rotating digits

## Accuracy (%) on Streaming Rotating MNIST→USPS

Method	MNIST Source	USPS	
		Target	OOD
Source-Only	97.8	28.8	24.9
DANN [27]	97.7	45.9	33.0
ADDA [28]	97.3	52.0	34.3
CIDA [30]	97.5	46.5	31.1
DSAN [29]	96.1	46.8	33.0
EDA [11]	<b>97.9</b>	45.5	31.9
ECBNN (Ours)	97.1	<b>60.9</b>	<b>38.5</b>

## Ablation study (Accuracy %)

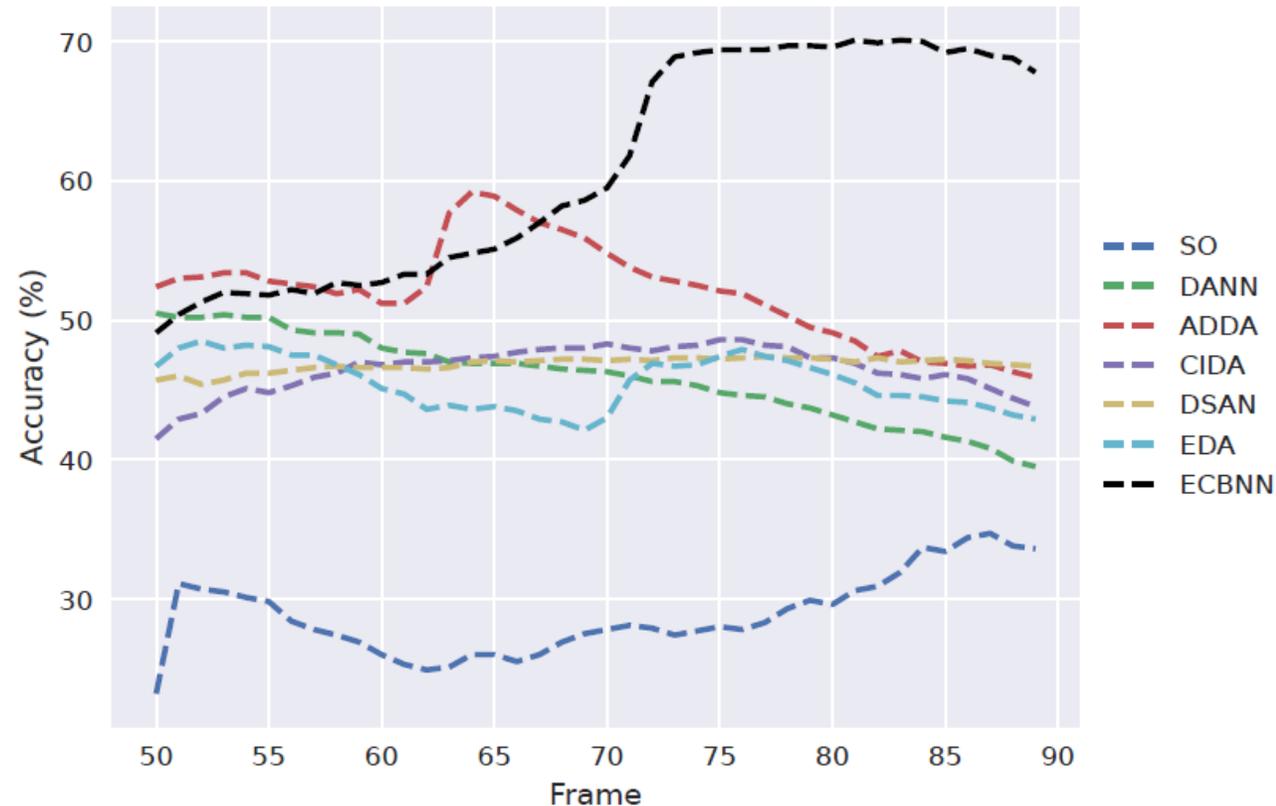
Method	Target Domain ↑	Out-of-Domain ↑
ECBNN (ours)	60.9	38.5
w/o $\tilde{l}_i$	53.6 (-7.3)	29.9 (-8.6)
w/o $\tilde{l}_i$ & w/o $l_{de}$	43.2 (-17.5)	28.0 (-9.5)

$\tilde{l}_i$  : upper bound of temporal-domain-invariant loss

$l_{de}$  : PFDE loss

# ECBNN can effectively “learn” from testing data in real-time!

Frame-wise accuracy on Streaming Rotating USPS testing set



# ECBNN can adapt with much lower latency during real-time testing stage!

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**Run time (s) for model adaptation and Accuracy (%) on OuluVS2 Dataset**

Method	Run time	Target
Source-Only	-	46.0
DANN [27]	-	71.5
ADDA [28]	-	69.3
CIDA [30]	-	63.0
DSAN [29]	-	66.4
EDA [11]	0.23	70.3
<b>ECBNN (Ours)</b>	<b>0.01</b>	<b>75.3</b>



**Thanks!**  
**Q&A on poster**

# Reference

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- Huang, H., Xue, F., Wang, H., & Wang, Y. (2020, November). Deep graph random process for relational-thinking-based speech recognition. In *International Conference on Machine Learning* (pp. 4531-4541). PMLR.
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